

Frameworks for Representing and Learning Abstract Causal Models

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Introduction

Background

Causal Abstraction with Soft Interventions

Causal Abstraction on Linear Models

Conclusions

Probabilistic models, such as **Bayesian Networks**, enable the representation of joint probabilities

$$\mathbb{P}(\text{☁️🌧️}, \text{☔️})$$



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Causal ordering is **not** necessary for probabilistic modelling.



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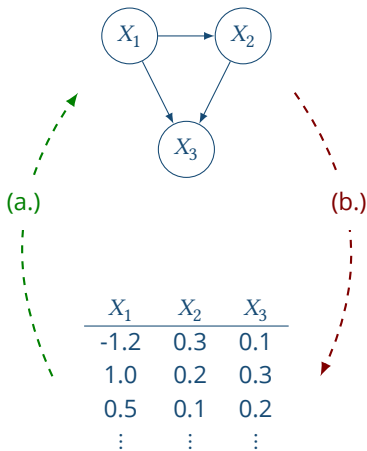
$$\mathbb{P}(\text{☁️}, \text{☔️})$$

Causal ordering is **not** necessary for probabilistic modelling.

...but it's needed to predict the effect of **interventions!**

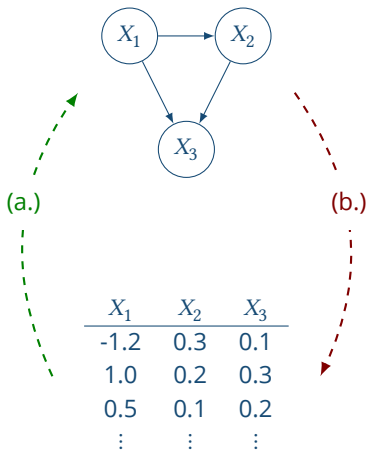


Learning causal models (a.) is challenging and generally requires non-observational data.

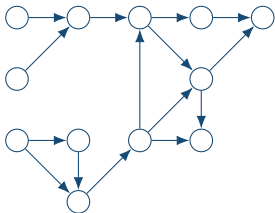


Learning causal models (a.) is challenging and generally requires non-observational data.

We can address it by restricting the **data generating process** (b.).

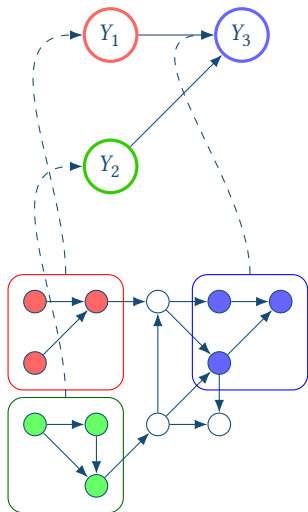


Causal relations might not be defined on the same **level of detail** of the observed variables.



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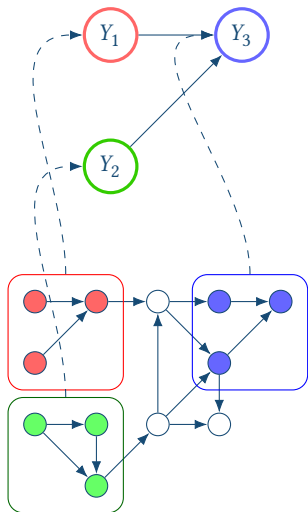
Causal Abstraction assumes the existence of higher-level aggregated *abstract* variables.



Causal relations might not be defined on the same **level of detail** of the observed variables.

Causal Abstraction assumes the existence of higher-level aggregated *abstract* variables.

Can we use this to understand or interpret **large** models?



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Causal Abstraction with Soft Interventions

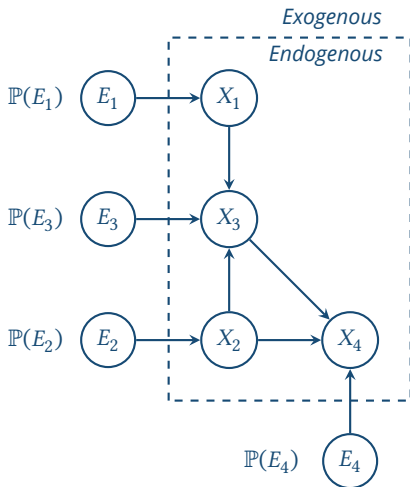
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A Structural Causal Model

$$\mathcal{M} = (X, E, f, \mathbb{P}_E),$$

specifies the deterministic mechanisms f between a set of endogenous variables X and a set of exogenous variables E with distribution \mathbb{P}_E .



To each *endogenous* variable $X \in \mathbf{X}$, we assign an *exogenous* variable $E_X \in \mathbf{E}$.

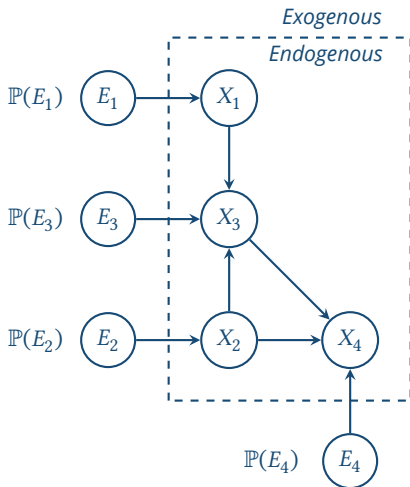
The endogenous mechanism f_X of X is then defined as a function

$$f_X : \mathcal{D}(\text{Pa}(X) \cup E_X) \rightarrow \mathcal{D}(X).$$

We define the model reduction

$$\mathcal{M} : \mathcal{D}(\mathbf{E}) \rightarrow \mathcal{D}(\mathbf{X}),$$

whenever the model is **acyclic**.



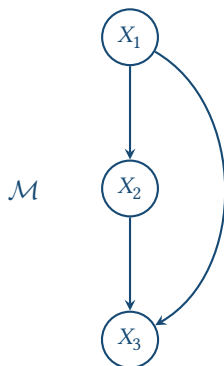
Given an SCM

$$\mathcal{M} = (\mathbf{X}, \mathbf{E}, \mathbf{f}, \mathbb{P}_{\mathbf{E}}),$$

a subset of variables $\mathbf{V} \subset \mathbf{X}$ and a setting $\mathbf{v} \in \mathcal{D}(\mathbf{V})$, a *hard* intervention $i = (\mathbf{V} \leftarrow \mathbf{v})$ results in a SCM $\mathcal{M}^i = (\mathbf{X}, \mathbf{E}, \mathbf{f}^i, \mathbb{P}_{\mathbf{E}})$, where

$$f_X^i = \begin{cases} v_X & X \in \mathbf{V} \\ f_X & X \notin \mathbf{V}, \end{cases}$$

for each endogenous variable $X \in \mathbf{X}$.



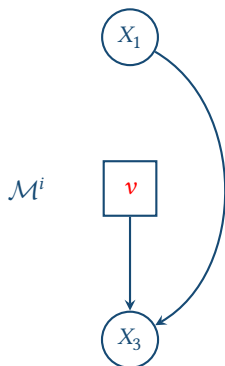
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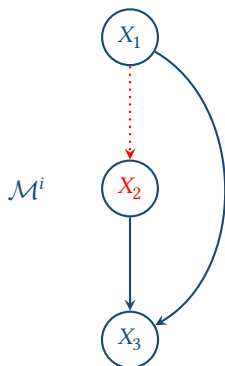
Given an SCM

$$\mathcal{M} = (\mathbf{X}, \mathbf{E}, \mathbf{f}, \mathbb{P}_{\mathbf{E}}),$$

a subset of variables $\mathbf{V} \subset \mathbf{X}$ and a set of functions \mathbf{h} , a *soft* intervention $i = (\mathbf{V} \leftarrow \mathbf{h})$ results in a SCM $\mathcal{M}^i = (\mathbf{X}, \mathbf{E}, \mathbf{f}^i, \mathbb{P}_{\mathbf{E}})$, where

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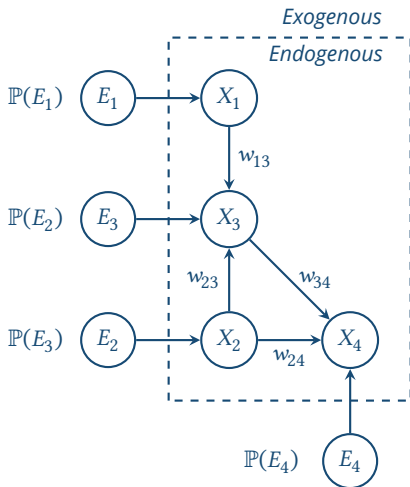
In a linear ANM, endogenous mechanisms have form

$$x_j = \sum_{X_i \in \text{Pa}(X_j)} w_{ij} x_i + e_j,$$

for each $X_j \in \mathbf{X}$.

The model reduction is

$$\begin{aligned} \mathcal{M}(\mathbf{e}) &= (\mathbf{I} - \mathbf{W})^{-1} \mathbf{e} \\ &= \mathbf{F}^\top \mathbf{e}. \end{aligned}$$



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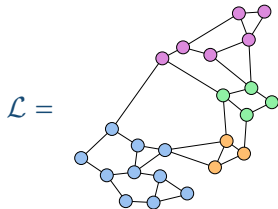
Conclusions

Low-Level SCM

Defined on variables X with
exogenous noise \mathbb{P}_E , structural
functions f , and interventions I .

Low-Level SCM

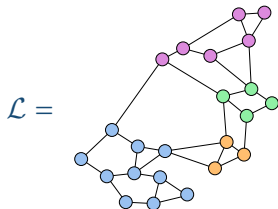
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Sensor data, raw measurements, or high-dimensional data.

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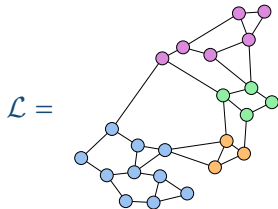
Sensor data, raw measurements, or high-dimensional data.

High-Level SCM

Defined on variables Y with exogenous noise \mathbb{P}_U , structural functions g , and interventions J .

Low-Level SCM

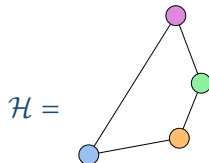
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Sensor data, raw measurements, or high-dimensional data.

High-Level SCM

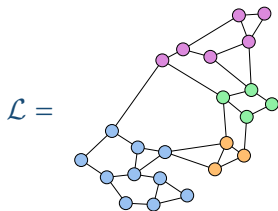
Defined on variables Y with exogenous noise \mathbb{P}_U , structural functions g , and interventions J .



Summary statistics, overviews, or low-dimensional data.

Low-Level SCM

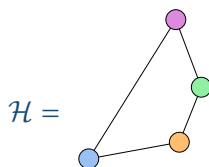
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Sensor data, raw measurements, or high-dimensional data.

High-Level SCM

Defined on variables Y with exogenous noise \mathbb{P}_U , structural functions g , and interventions J .



Summary statistics, overviews, or low-dimensional data.

$$|\mathbf{X}| \gg |\mathbf{Y}|$$

Given two SCMs

- $\mathcal{L} = (X, E, f, \mathbb{P}_E)$ with admissible interventions I ,
- $\mathcal{H} = (Y, U, g, \mathbb{P}_U)$ with admissible interventions J ,

Causal Abstraction consists of two *surjective* functions

Given two SCMs

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Causal Abstraction consists of two *surjective* functions

- $\tau: \mathcal{D}(X) \rightarrow \mathcal{D}(Y)$ (Endogenous Map)

Given two SCMs

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Causal Abstraction consists of two *surjective* functions

- $\tau: \mathcal{D}(X) \rightarrow \mathcal{D}(Y)$ (Endogenous Map)
- $\gamma: \mathcal{D}(E) \rightarrow \mathcal{D}(U)$ (Exogenous Map)

Given two SCMs

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- $\mathcal{H} = (Y, U, g, \mathbb{P}_U)$ with admissible interventions J ,

Causal Abstraction consists of two *surjective* functions

- $\tau: \mathcal{D}(X) \rightarrow \mathcal{D}(Y)$ (Endogenous Map)
- $\gamma: \mathcal{D}(E) \rightarrow \mathcal{D}(U)$ (Exogenous Map)

that induce a unique intervention map $\omega: I \rightarrow J$ such that

$$\omega(i) = j \iff \text{Rst}(j) = \{\tau(\mathbf{x}) \mid \mathbf{x} \in \text{Rst}(i)\}$$

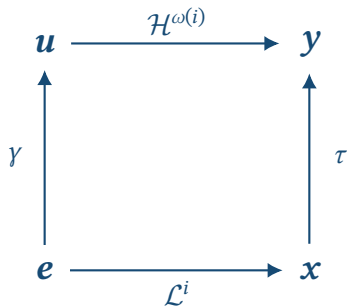
$$\text{Rst}(V \leftarrow \mathbf{v}) = \{\mathbf{x} \mid \mathbf{x}_V = \mathbf{v}\}$$

\mathcal{H} is a τ -abstraction of \mathcal{L} .

\Leftrightarrow

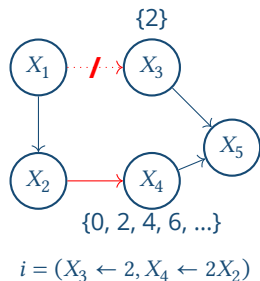
$$\tau \circ \mathcal{L}^i = \mathcal{H}^{\omega(i)} \circ \gamma$$

\mathcal{H} is a τ -abstraction of \mathcal{L} .



 The intervention map is defined for **hard** interventions only.

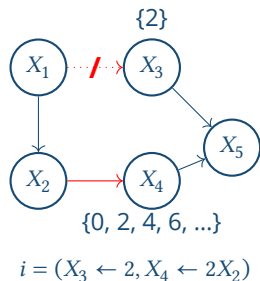
 The intervention map does not have an **explicit form**.



The **Soft Restriction** of an intervention $i = (V \leftarrow h)$ contains all the values that an intervened model can assume.

$$\begin{aligned} \text{SoftRst}(\mathcal{M}^i) &= \{x \in \mathbb{R}^5 \mid x_3 = 2, x_4 \in \text{Image}(\lambda x.2x)\} \\ &= \{x \in \mathbb{R}^5 \mid x_3 = 2, \text{Even}(x_4)\}. \end{aligned}$$

$$\begin{bmatrix} 0.5 \\ -0.2 \\ 2 \\ 16 \\ 9.4 \end{bmatrix} \in \text{SoftRst}(\mathcal{M}^i), \quad \begin{bmatrix} 0.5 \\ -0.2 \\ 2 \\ 7 \\ 9.4 \end{bmatrix} \notin \text{SoftRst}(\mathcal{M}^i)$$



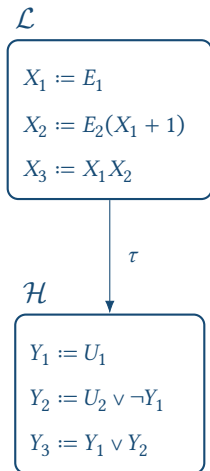
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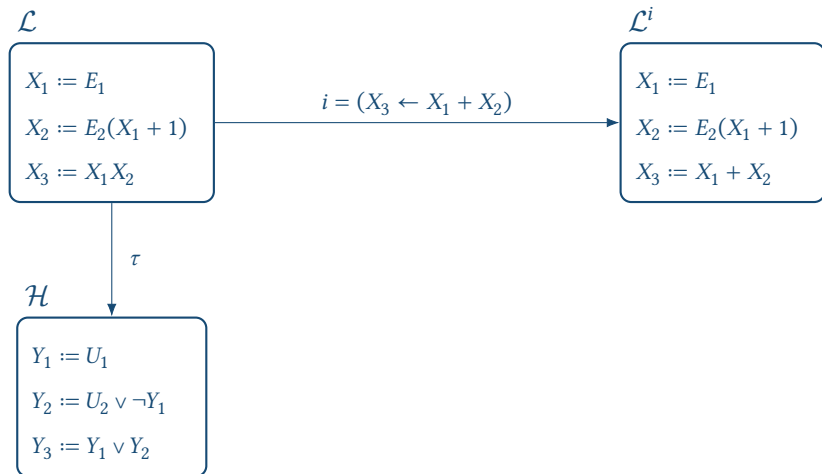
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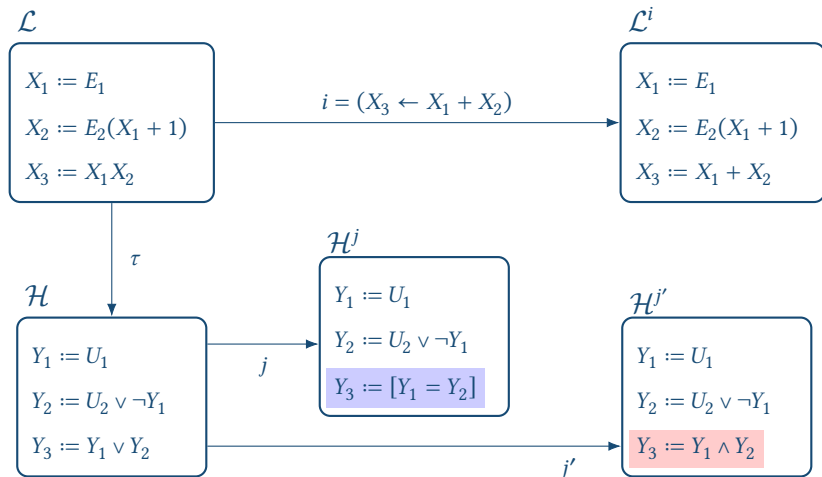
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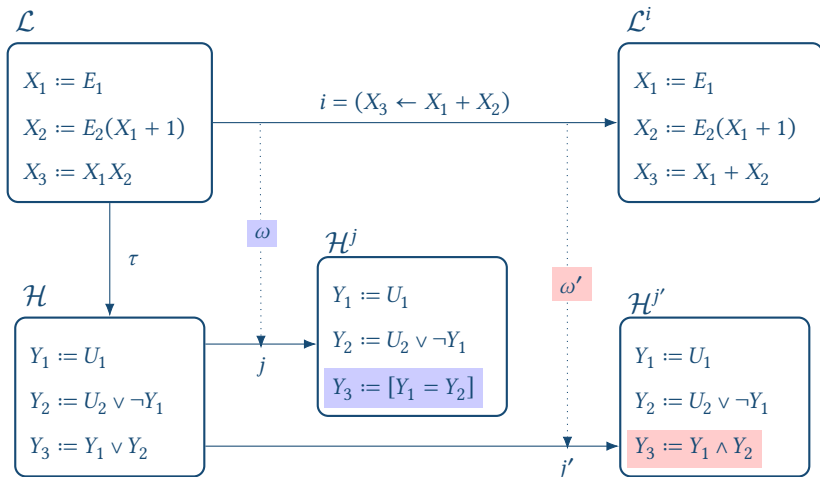
Then, we define ω as

$$\omega(i) = j \iff \text{SoftRst}(\mathcal{H}^j) = \{\tau(x) \mid x \in \text{SoftRst}(\mathcal{L}^i)\}.$$









Y_1	Y_2	$Y_1 \wedge Y_2$	$[Y_1 = Y_2]$
F	F	F	T
F	T	F	F
T	F	F	F
T	T	T	T

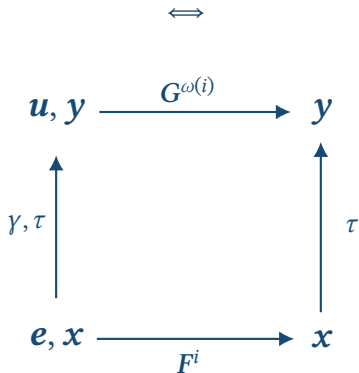
The two high-level interventions differ only for values that are **never** reached by the model for any exogenous configuration.

\mathcal{H} is a τ -abstraction of \mathcal{L} on **soft** interventions

\Leftrightarrow

$$\tau \circ F^i = G^{\omega(i)} \circ [\gamma, \tau]$$

\mathcal{H} is a τ -abstraction of \mathcal{L} on **soft** interventions



By generalizing the restriction set and testing consistency for each abstract variable, we can uniquely define ω for *soft interventions* such that

$$\omega(i) = (Y \leftarrow \tau_Y \circ F^i \circ \tau_{\text{Pa}(Y)}^{-1})$$

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 Which causal **graphs** are consistent with abstraction?

 Which causal **mechanisms** are consistent with abstraction?

\mathcal{H} is a \mathbf{T} -abstraction of \mathcal{L}



\mathcal{H} is a τ -abstraction of \mathcal{L} and $\tau(x) = \mathbf{T}^\top x$, where $\mathbf{T} \in \mathbb{R}^{|\mathbf{X}| \times |\mathbf{Y}|}$.

$$\mathbf{T} = \begin{array}{c} \left| \begin{array}{ccc} \mathbf{0.43} & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{0.71} & 0 & 0 \\ 0 & \mathbf{0.52} & 0 \\ 0 & \mathbf{-0.12} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \mathbf{0.98} \end{array} \right| \end{array}$$

The set of relevant variables of an abstract variable $Y \in \mathcal{Y}$ is the subset of concrete variables $\Pi_R(Y)$ on which it depends through \mathbf{T} .

$$\mathbf{T} = \begin{array}{c} \left| \begin{array}{ccc} \mathbf{0.43} & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{0.71} & 0 & 0 \\ 0 & \mathbf{0.52} & 0 \\ 0 & \mathbf{-0.12} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \mathbf{0.98} \end{array} \right| \end{array}$$

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Lemma 6.3.1, p. 4:

Relevant variables **must** be disjoint.

As a consequence of disjointness and linearity, the intervention map ω is uniquely defined.

$$\omega(\mathbf{V} \leftarrow \mathbf{v}) = (Y \leftarrow y) \iff \mathbf{V} = \Pi_R(Y) \text{ and } y = \mathbf{t}_Y^\top \mathbf{v}.$$

A directed path between two variables is \mathbf{T} -direct if and only if any other variable on the path is not relevant.



$$X_1 \xrightarrow{\mathbf{T}} X_4$$

T-direct Path

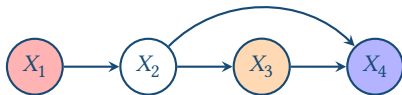
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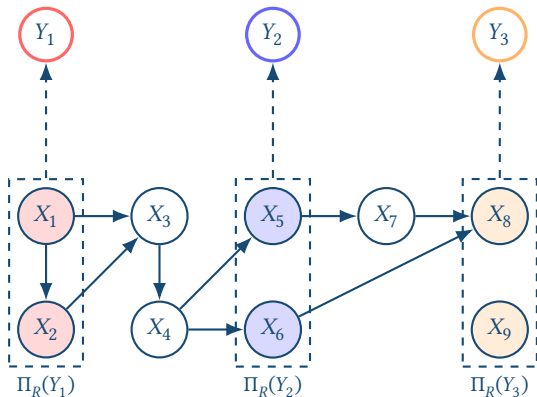
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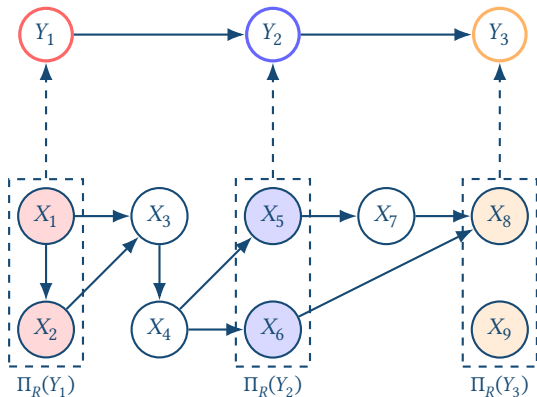
Lemma 6.3.3, p. 77:

Let $X_1 \in \Pi_R(Y_1)$ and $X_2 \in \Pi_R(Y_2)$. If $X_1 \xrightarrow{T} X_2$ in \mathcal{L} , then



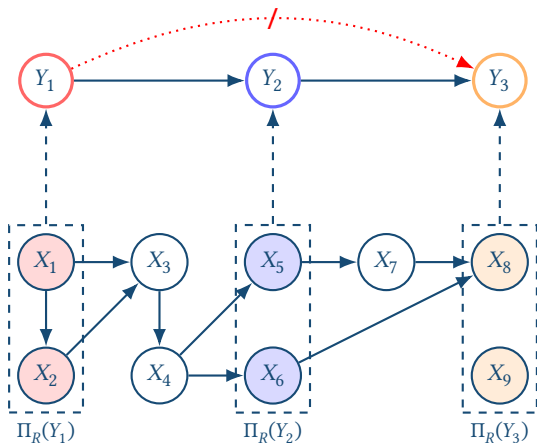
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Let $X_1 \in \Pi_R(Y_1)$ and $X_2 \in \Pi_R(Y_2)$. If $X_1 \xrightarrow{T} X_2$ in \mathcal{L} , then $Y_1 \rightarrow Y_2$ in \mathcal{H} .

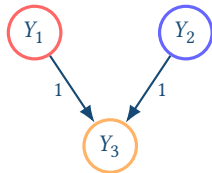
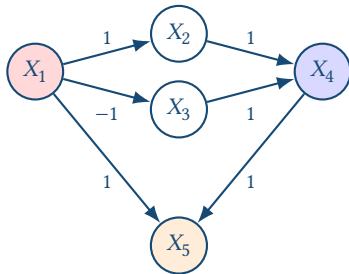


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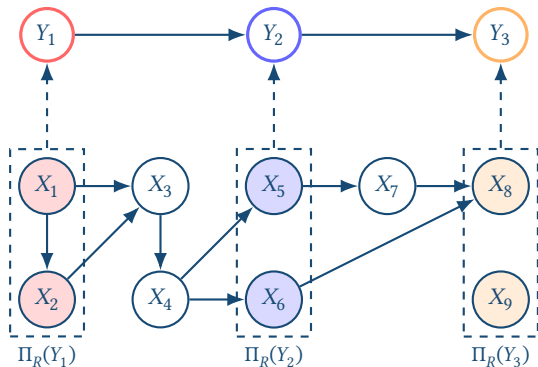


With cancelling paths, things get nasty!



Theorem 6.3.5, p. 78:

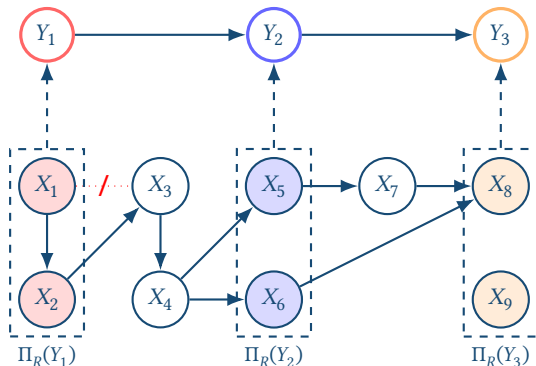
Let $Y_1 \rightarrow Y_2$ in \mathcal{H} . Then, $\forall X_1 \in \Pi_R(Y_1), \exists X_2 \in \Pi_R(Y_2)$ s.t. $X_1 \xrightarrow{\tau} X_2$ in \mathcal{L} .



\mathcal{H} is a τ -abstraction of \mathcal{L}

Theorem 6.3.5, p. 78:

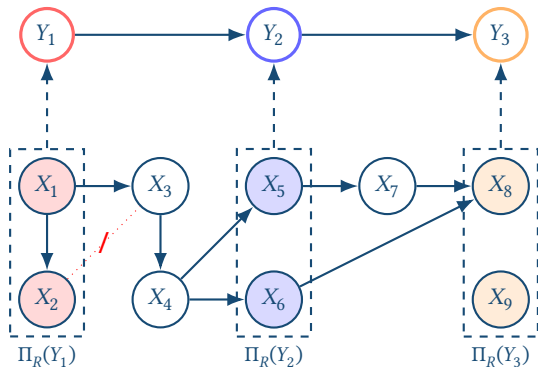
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\mathcal{H} is **not** a τ -abstraction of \mathcal{L}

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Let $Y_1 \rightarrow Y_2$ in \mathcal{H} . Then, $\forall X_1 \in \Pi_R(Y_1), \exists X_2 \in \Pi_R(Y_2)$ s.t. $X_1 \xrightarrow{\tau} X_2$ in \mathcal{L} .



\mathcal{H} is **not** a τ -abstraction of \mathcal{L}

The exogenous abstraction function is a linear transformation

$$\gamma(e) = \mathbf{S}^\top e,$$

where $\mathbf{S} = \mathbf{F}^\top \mathbf{G}^{-1}$.

$$\mathbf{S} = \begin{array}{c|ccc} & \mathbf{0.43} & 0 & 0 \\ & \mathbf{0.22} & 0 & 0 \\ & \mathbf{0.71} & 0 & 0 \\ & 0 & \mathbf{0.52} & 0 \\ & 0 & \mathbf{-0.12} & 0 \\ & 0 & 0 & \mathbf{-1.02} \\ & 0 & 0 & \mathbf{0.98} \end{array}$$

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The set of **block** variables of an abstract variable $Y \in \mathcal{Y}$ is the subset of concrete variables $\Pi(Y)$ on which it depends through \mathbf{S} .

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The set of **block** variables of an abstract variable $Y \in \mathcal{Y}$ is the subset of concrete variables $\Pi(Y)$ on which it depends through \mathbf{S} .

Lemma 6.3.8, p. 81:

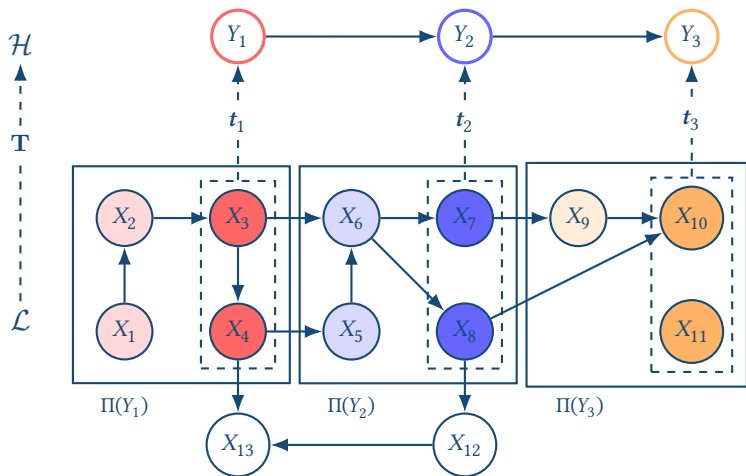
Relevant variables are a subset of block variables.

Lemma 6.3.9, p. 82:

Block variables must be disjoint.

Theorem 6.3.10, p. 82:

Block variables follow abstract ordering.



\mathcal{H} is a \mathbf{T} -abstraction of \mathcal{L}

\Leftrightarrow

$$\tau \circ \mathcal{L}^i = \mathcal{H}^{\omega(i)} \circ \gamma$$

\mathcal{H} is a \mathbf{T} -abstraction of \mathcal{L}

\iff

$$Y_i \prec_{\mathcal{H}} Y_j \iff \Pi(Y_i) \prec_{\mathcal{L}} \Pi(Y_j)$$

$$\mathbf{W}_{ij} \mathbf{s}_j = m_{ij} \mathbf{t}_i$$

\mathcal{H} is a \mathbf{T} -abstraction of \mathcal{L}

\iff

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This characterization enables testing for \mathbf{T} -abstraction in closed form.

Assuming **non-Gaussian noise**, linear ANMs are identifiable from observational data (Shimizu et al. 2006).

$$\mathbf{e}^{(i)} \sim \text{Exponential for } i = 1, \dots, |\mathcal{D}_{\mathcal{L}}|,$$

$$\mathbf{x}^{(i)} = \mathcal{L}(\mathbf{e}^{(i)}) \quad \text{for } i = 1, \dots, |\mathcal{D}_{\mathcal{L}}|,$$

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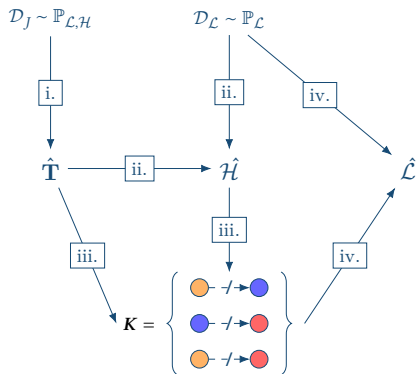
What about abstractions?

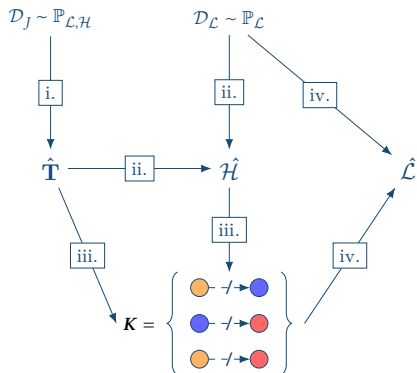
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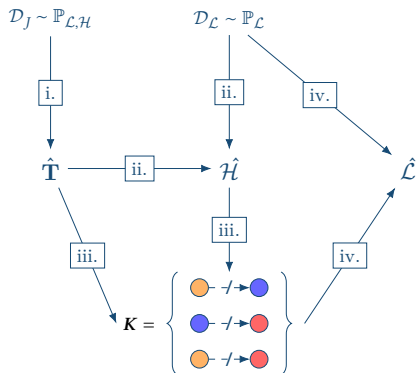
$$\mathbf{y}^{(i)} = \mathcal{H}(\gamma(\mathbf{e}^{(i)})) \quad \text{for } i = 1, \dots, |\mathcal{D}_{\mathcal{J}}|,$$

such that $|\mathcal{D}_{\mathcal{J}}| \ll |\mathcal{D}_{\mathcal{L}}|$.

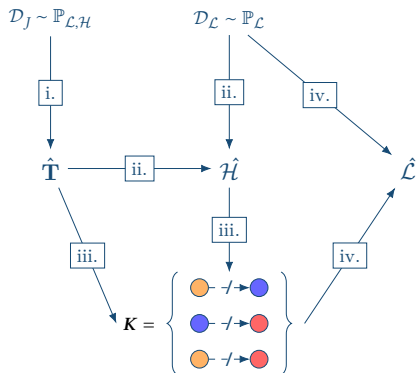




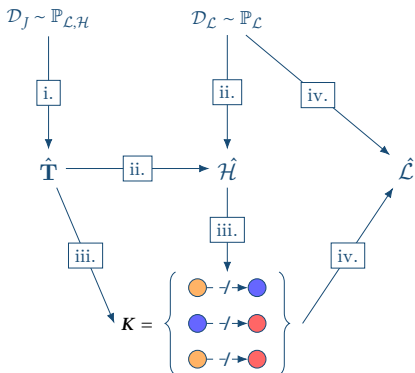
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- i. Recover $\hat{\mathbf{T}}$ from \mathcal{D}_J
- ii. Abstract \mathcal{D}_L and recover $\hat{\mathcal{H}}$
- iii. Define constraints \mathbf{K} from $\hat{\mathcal{H}}, \hat{\mathbf{T}}$



- Recover $\hat{\mathbf{T}}$ from \mathcal{D}_J
- Abstract $\mathcal{D}_{\mathcal{L}}$ and recover $\hat{\mathcal{H}}$
- Define constraints \mathbf{K} from $\hat{\mathcal{H}}$, $\hat{\mathbf{T}}$
- Recover $\hat{\mathcal{L}}$ from $\mathcal{D}_{\mathcal{L}}$ and \mathbf{K}

Algorithm 1: Abs-LiNGAM

Input: Concrete Observational Dataset $\mathcal{D}_{\mathcal{L}}$,
 Joint Observational Dataset \mathcal{D}_J .

Result: Abstraction function $\hat{\mathbf{T}} \in \mathbb{R}^{d \times b}$,
 Abstract adjacency matrix $\hat{\mathbf{M}} \in \mathbb{R}^{b \times b}$,
 Concrete adjacency matrix $\hat{\mathbf{W}} \in \mathbb{R}^{d \times d}$.

$\hat{\mathbf{T}} \leftarrow \arg \min_{\mathbf{T} \in \mathbb{R}^{b \times d}} \sum_{(x,y) \in \mathcal{D}_J} \|\mathbf{x}^\top \mathbf{T} - \mathbf{y}^\top\|_2^2;$

for $Y_i \in Y$ **do**

$\hat{\Pi}_R(Y_i) \leftarrow \{X_k \in X \mid [\hat{f}_i]_k \neq 0\}$

end

$\mathcal{D}_{\hat{\mathcal{H}}} \leftarrow \{\hat{\mathbf{T}}^\top \mathbf{x} \mid \mathbf{x} \in \mathcal{D}_{\mathcal{L}}\}$

$\hat{\mathbf{M}} \leftarrow \text{DirectLiNGAM}(\mathcal{D}_{\hat{\mathcal{H}}}, \emptyset)$

$K \leftarrow \emptyset$

for $Y_i, Y_j \in Y$ **do**

if $Y_i \not\rightarrow Y_j$ **then**

for $X_k \in \hat{\Pi}_R(Y_i), X_h \in \hat{\Pi}_R(Y_j)$ **do**

$K \leftarrow K \cup \{X_k \not\rightarrow X_h\}$

end

end

end

$\hat{\mathbf{W}} \leftarrow \text{DirectLiNGAM}(\mathcal{D}_{\mathcal{L}}, K)$

▷ Select Relevant Variables

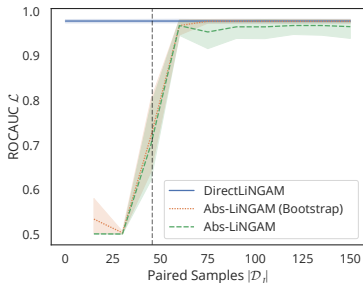
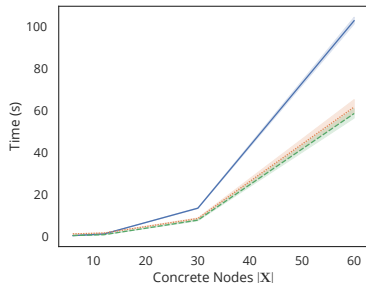
▷ Create Abstract Dataset

▷ Abstract Discovery

▷ Collect Prior Knowledge

▷ Check Ancestorship in $\hat{\mathbf{M}}$

▷ Concrete Discovery

(a) Performance over Paired Samples $|\mathcal{D}_J|$ (b) Execution Time (s) over Graph Size $|X|$

Introducing abstract information in the LiNGAM pipeline, we gain significant speedup (2x) in execution time (b, *right*) without performance loss (a, *left*) on the retrieval of the concrete model ($|X| \in [25, 50]$, $|Y| = 5$).

Introduction

Background

Causal Abstraction with Soft Interventions

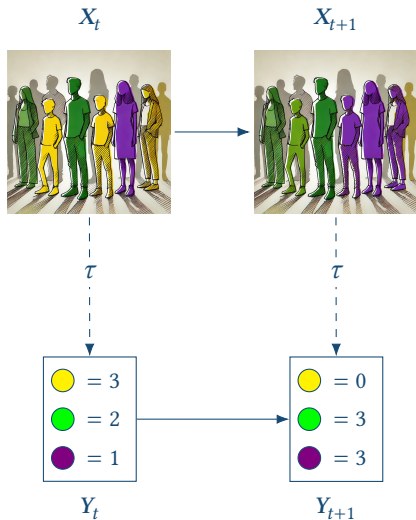
Causal Abstraction on Linear Models

Conclusions

Surrogate models are usually trained for **predictive** tasks.

Causal Abstraction enables the training of interventionally consistent surrogate models.

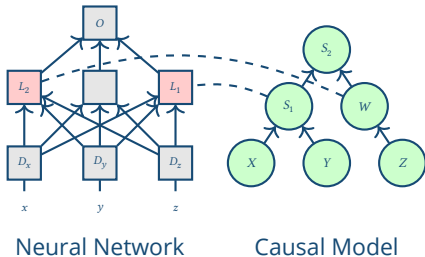
Dyer et al. (2024) shows how to fasten policy evaluation by abstracting SIRS epidemiological models.

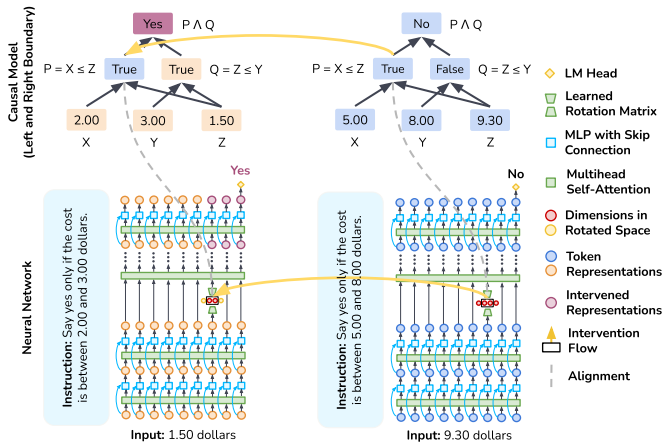


The **interpretation** of neural networks is strongly related to causal queries: why? what if?

Causal Abstraction provides a framework to determine whether a neural network implements a causal model.

Geiger, Wu, et al. (2021) also shows how to enforce causal constraints when training neural networks.





It works for LLMs too!

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- **Causal Abstraction** enables concise representation of complex causal relations.
- τ -abstraction provides a and explicit **intervention map** for generic causal models.
- For **linear** models, we have sound guarantees on both graphical and functional properties.
- Applications exploit **abstract** causal properties to understand and interpret complex models.

-  Beckers, Sander and Joseph Y. Halpern (2019). **“Abstracting Causal Models”**. In: *Proceedings of the Thirty-Third AAAI Conference on Artificial Intelligence and Thirty-First Innovative Applications of Artificial Intelligence Conference and Ninth AAAI Symposium on Educational Advances in Artificial Intelligence*. Vol. 33. AAAI’19/IAAI’19/EAAI’19. Honolulu, Hawaii, USA: AAAI Press, pp. 2678–2685. isbn: 978-1-57735-809-1. doi: 10.1609/aaai.v33i01.33012678. url: <https://doi.org/10.1609/aaai.v33i01.33012678>.
-  Dyer, Joel et al. (2024). **“Interventionally Consistent Surrogates for Complex Simulation Models”**. In: *The Thirty-eighth Annual Conference on Neural Information Processing Systems*.
-  Geiger, Atticus, Hanson Lu, et al. (2021). **“Causal abstractions of neural networks”**. In: *Advances in Neural Information Processing Systems 34*, pp. 9574–9586.

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